

Medium Payload Intelligent Robot

FANUC Robot -710iC

Features

The M-710iC is a medium payload robot with a wrist payload of 12 - 70kg. Seven models are available for a wide variety of applications.

- FANUC Robot M-710iC/45M, /50, /70

Wide motion envelope and enough wrist load capacity to handle a large panel.

M-710iC/45M : Payload capacity 45kg

M-710iC/50 : Payload capacity 50kg

M-710iC/70 : Payload capacity 70kg

- FANUC Robot M-710iC/50S

This model has a compact body that is suitable for narrow work environments. (Payload capacity 50kg)

- FANUC Robot M-710iC/12L, /20L, /20M

Long reach and high motion performance make it suitable for many applications, such as handling, sealing and arc welding.

M-710iC/12L : Payload capacity 12kg (Hollow wrist)

M-710iC/20L : Payload capacity 20kg

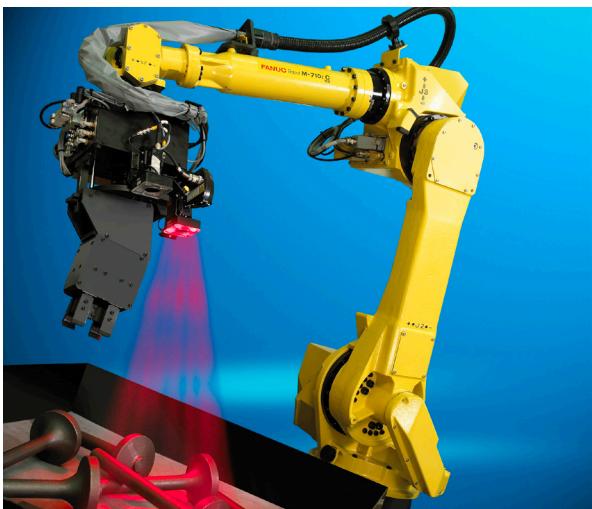
M-710iC/20M : Payload capacity 20kg

- FANUC Robot M-710iC/50H

This five-axes model is designed for the high speed transferring of parts. The ceiling mount option is ideal for compact handling systems. (Payload capacity 50kg)

- The full cover provides IP67-equivalent resistance to environmental conditions (dust and liquid). The M-710iC is reliable for various applications, such as load/unload for machined parts, de-burring and die cast loading.

Application system



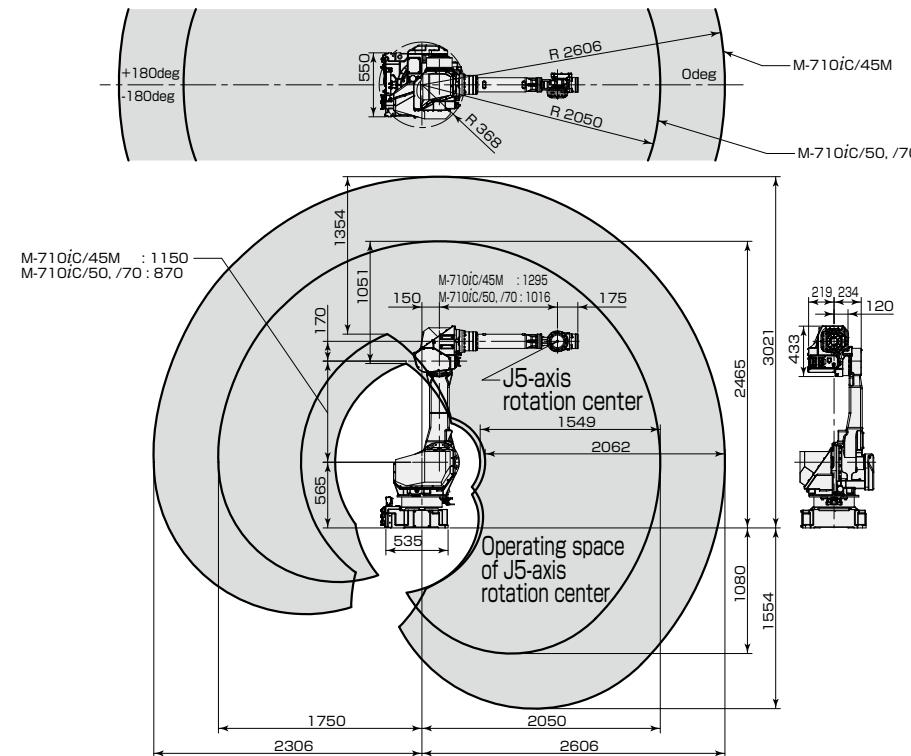
Bin picking of cylindrical parts



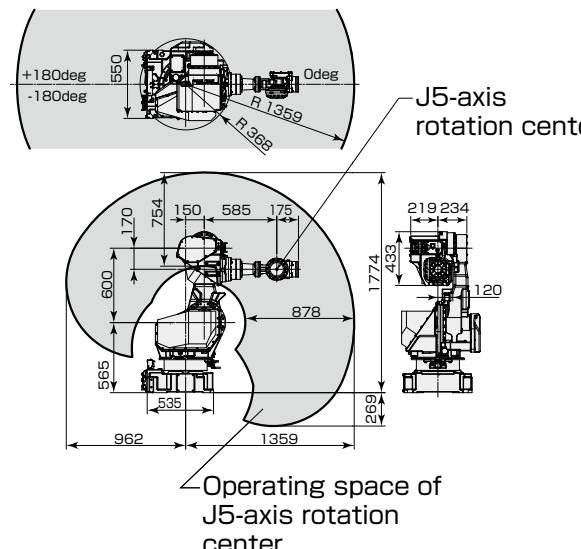
Car body sealing

Operating space

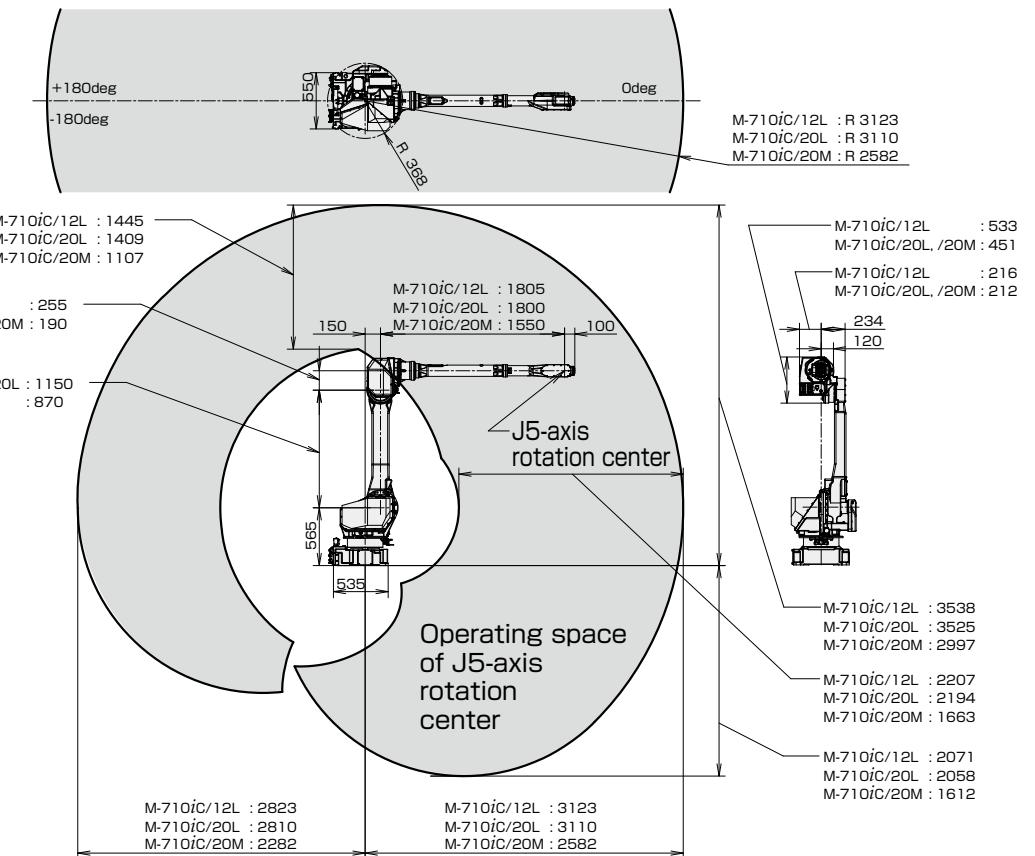
M-710iC/45M,/50,/70



M-710iC/50S



M-710iC/12L,/20L,/20M



Specifications

Model	M-710iC/45M	M-710iC/50	M-710iC/70
Type	Articulated Type		
Controlled axes	6 axes (J1, J2, J3, J4, J5, J6)		
Reach	2606mm		
Installation (Note 1)	Floor, Upside-down, Angle mount		
Motion range (Maximum speed) (Note 2)	J1 axis rotation 360° (180°/s) 6.28 rad (3.14 rad/s)	J1 axis rotation 360° (175°/s) 6.28 rad (3.05 rad/s)	J1 axis rotation 360° (160°/s) 6.28 rad (2.79 rad/s)
	J2 axis rotation 225° (180°/s) 3.93 rad (3.14 rad/s)	J2 axis rotation 225° (175°/s) 3.93 rad (3.05 rad/s)	J2 axis rotation 225° (120°/s) 3.93 rad (2.09 rad/s)
	J3 axis rotation 440° (180°/s) 7.68 rad (3.14 rad/s)	J3 axis rotation 440° (175°/s) 7.68 rad (3.05 rad/s)	J3 axis rotation 440° (120°/s) 7.68 rad (2.09 rad/s)
	J4 axis wrist rotation 800° (250°/s) 13.96 rad (4.36 rad/s)	J4 axis wrist rotation 720° (250°/s) 12.57 rad (4.36 rad/s)	J4 axis wrist rotation 720° (225°/s) 12.57 rad (3.93 rad/s)
	J5 axis wrist swing 250° (250°/s) 4.36 rad (4.36 rad/s)	J5 axis wrist swing 250° (250°/s) 4.36 rad (4.36 rad/s)	J5 axis wrist swing 250° (225°/s) 4.36 rad (3.93 rad/s)
	J6 axis wrist rotation 800° (360°/s) 13.96 rad (6.28 rad/s)	J6 axis wrist rotation 720° (355°/s) 12.57 rad (6.20 rad/s)	J6 axis wrist rotation 720° (325°/s) 12.57 rad (6.20 rad/s)
Max. load capacity at wrist	45kg	50kg	70kg
Max. Load capacity at J3 casing (Note 3)	15kg		
Allowable load moment at wrist	J4 axis 206 N·m 21 kgf·m	J4 axis 294 N·m 30 kgf·m	J4 axis 206 N·m 21 kgf·m
	J5 axis 206 N·m 21 kgf·m	J5 axis 294 N·m 30 kgf·m	J5 axis 206 N·m 21 kgf·m
	J6 axis 127 N·m 13 kgf·m	J6 axis 147 N·m 15 kgf·m	J6 axis 127 N·m 13 kgf·m
Allowable load inertia at wrist	J4 axis 28 kg·m² 286 kgf·cm·s²	J4 axis 28 kg·m² 286 kgf·cm·s²	J4 axis 28 kg·m² 286 kgf·cm·s²
	J5 axis 28 kg·m² 286 kgf·cm·s²	J5 axis 28 kg·m² 286 kgf·cm·s²	J5 axis 28 kg·m² 286 kgf·cm·s²
	J6 axis 20 kg·m² 204 kgf·cm·s²	J6 axis 11 kg·m² 112 kgf·cm·s²	J6 axis 11 kg·m² 112 kgf·cm·s²
Drive method	Electric servo drive by AC servo motor		
Positioning accuracy	± 0.1 mm	± 0.07 mm	
Mass (Note 4)	570 kg	560 kg	
Installation environment	Ambient temperature : 0~45°C Ambient humidity : Normally 75%RH or less (No dew nor frost allowed) Short term 95%RH or less (within one month) Vibration acceleration : 4.9m/s² (0.5G) or less		

Note 1) In case of the angle mounting, the J1 and J2 axis motion range are restricted.

Note 2) During short distance motions, the axis speed may not reach the maximum value stated.

Note 3) Max. load capacity at J3 casing is limited by payload at wrist.

Note 4) Without controller.

Specifications

Model	M-710iC/50S
Type	Articulated Type
Controlled axes	6 axes (J1, J2, J3, J4, J5, J6)
Reach	1359mm
Installation (Note 1)	Floor, Upside-down, Angle mount
Motion range (Maximum speed) (Note 2)	J1 axis rotation 360° (175°/s) 6.28 rad (3.05 rad/s)
	J2 axis rotation 169° (175°/s) 2.95 rad (3.05 rad/s)
	J3 axis rotation 376° (175°/s) 6.56 rad (3.05 rad/s)
	J4 axis wrist rotation 720° (250°/s) 12.57 rad (4.36 rad/s)
	J5 axis wrist swing 250° (250°/s) 4.36 rad (4.36 rad/s)
	J6 axis wrist rotation 720° (355°/s) 12.57 rad (6.20 rad/s)
Max. load capacity at wrist	50kg
Max. Load capacity at J3 casing (Note 3)	15kg
Allowable load moment at wrist	J4 axis 206 N·m 21 kgf·m
	J5 axis 206 N·m 21 kgf·m
	J6 axis 127 N·m 13 kgf·m
Allowable load inertia at wrist	J4 axis 28 kg·m² 286 kgf·cm·s²
	J5 axis 28 kg·m² 286 kgf·cm·s²
	J6 axis 11 kg·m² 112 kgf·cm·s²
Drive method	Electric servo drive by AC servo motor
Positioning accuracy	± 0.07 mm
Mass (Note 4)	545 kg
Installation environment	Ambient temperature : 0~45°C Ambient humidity : Normally 75%RH or less (No dew nor frost allowed) Short term 95%RH or less (within one month) Vibration acceleration : 4.9m/s² (0.5G) or less

Note 1) In case of the angle mounting, the J1 and J2 axis motion range are restricted.

Note 2) During short distance motions, the axis speed may not reach the maximum value stated.

Note 3) Max. load capacity at J3 casing is limited by payload at wrist.

Note 4) Without controller.

Specifications

Model	M-710iC/12L	M-710iC/20L	M-710iC/20M
Type	Articulated Type		
Controlled axes	6 axes (J1, J2, J3, J4, J5, J6)		
Reach	3123mm		
Installation (Note 1)	Floor, Upside-down, Angle mount		
Motion range (Maximum speed) (Note 2)	J1 axis rotation 360° (180°/s) 6.28 rad (3.14 rad/s)	J1 axis rotation 360° (175°/s) 6.28 rad (3.05 rad/s)	J1 axis rotation 360° (175°/s) 6.28 rad (3.05 rad/s)
	J2 axis rotation 225° (180°/s) 3.93 rad (3.14 rad/s)	J2 axis rotation 225° (175°/s) 3.93 rad (3.05 rad/s)	J2 axis rotation 225° (175°/s) 3.93 rad (3.05 rad/s)
	J3 axis rotation 434° (180°/s) 7.57 rad (3.14 rad/s)	J3 axis rotation 432° (180°/s) 7.54 rad (3.14 rad/s)	J3 axis rotation 435° (180°/s) 7.59 rad (3.14 rad/s)
	J4 axis wrist rotation 400° (400°/s) 6.98 rad (6.98 rad/s)	J4 axis wrist rotation 400° (350°/s) 6.98 rad (6.11 rad/s)	J4 axis wrist rotation 400° (350°/s) 6.98 rad (6.11 rad/s)
	J5 axis wrist swing 380° (430°/s) 6.63 rad (7.50 rad/s)	J5 axis wrist swing 280° (360°/s) 4.89 rad (6.28 rad/s)	J5 axis wrist swing 280° (360°/s) 4.89 rad (6.28 rad/s)
	J6 axis wrist rotation 720° (630°/s) 12.57 rad (11.0 rad/s)	J6 axis wrist rotation 900° (600°/s) 15.71 rad (10.47 rad/s)	J6 axis wrist rotation 900° (600°/s) 15.71 rad (10.47 rad/s)
Max. load capacity at wrist	12kg	20kg	
Max. Load capacity at J3 casing (Note 3)	24kg		
Allowable load moment at wrist	J4 axis 22.0 N·m 2.24 kgf·m	J4 axis 39.2 N·m 4.0 kgf·m	
	J5 axis 22.0 N·m 2.24 kgf·m	J5 axis 39.2 N·m 4.0 kgf·m	
	J6 axis 9.8 N·m 1.0 kgf·m	J6 axis 19.6 N·m 2.0 kgf·m	
Allowable load inertia at wrist	J4 axis 0.65 kg·m² 6.6 kgf·cm·s²	J4 axis 0.88 kg·m² 9.0 kgf·cm·s²	J4 axis 0.65 kg·m² 6.6 kgf·cm·s²
	J5 axis 0.65 kg·m² 6.6 kgf·cm·s²	J5 axis 0.88 kg·m² 9.0 kgf·cm·s²	J5 axis 0.65 kg·m² 6.6 kgf·cm·s²
	J6 axis 0.17 kg·m² 1.7 kgf·cm·s²	J6 axis 0.25 kg·m² 2.6 kgf·cm·s²	J6 axis 0.17 kg·m² 1.7 kgf·cm·s²
Drive method	Electric servo drive by AC servo motor		
Positioning accuracy	± 0.15 mm		
Mass (Note 4)	540 kg	530 kg	
Installation environment	Ambient temperature : 0~45°C Ambient humidity : Normally 75%RH or less (No dew nor frost allowed) Short term 95%RH or less (within one month) Vibration acceleration : 4.9m/s² (0.5G) or less		

Note 1) In case of the angle mounting, the J1 and J2 axis motion range are restricted.

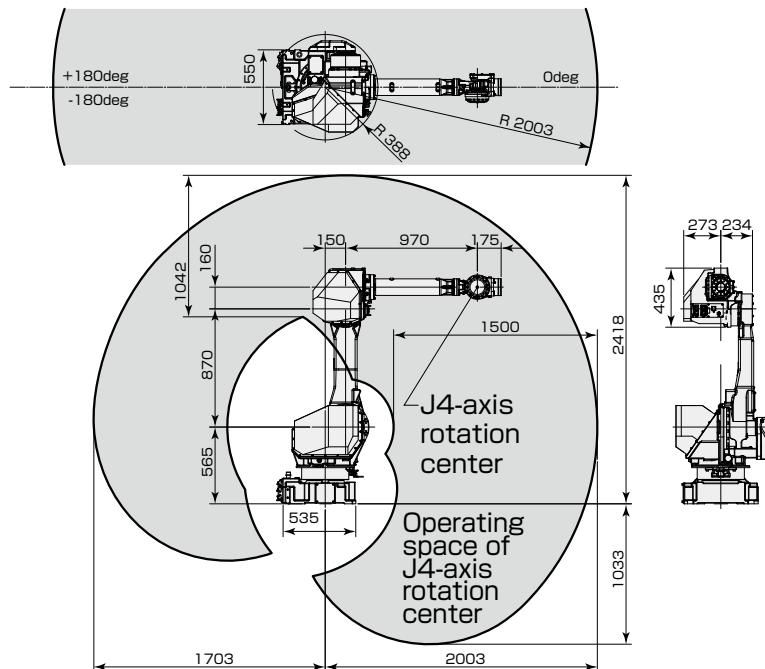
Note 2) During short distance motions, the axis speed may not reach the maximum value stated.

Note 3) Max. load capacity at J3 casing is limited by payload at wrist.

Note 4) Without controller.

Operating space

M-710iC/50H



Specifications

Model		M-710iC/50H
Type		Articulated Type
Controlled axes		5 axes (J1, J2, J3, J4, J5)
Reach		2003mm
Installation		Floor, Upside-down
Motion range (Maximum speed) (Note 1)	J1 axis rotation	360° (175°/s) 6.28 rad (3.05 rad/s)
	J2 axis rotation	225° (175°/s) 3.93 rad (3.05 rad/s)
	J3 axis rotation	440° (175°/s) 7.68 rad (3.05 rad/s)
	J4 axis wrist swing	234° (175°/s) 4.08 rad (3.05 rad/s)
	J5 axis wrist rotation	720° (720°/s) 12.57 rad (12.57 rad/s)
Max. load capacity at wrist		50kg
Max. load capacity at J3 casing (Note 2)		15kg
Allowable load moment at wrist	J4 axis	150 N·m 15.3 kgf·m
	J5 axis	68 N·m 6.9 kgf·m
Allowable load inertia at wrist	J4 axis	6.3 kg·m ² 64.3 kgf·cm·s ²
	J5 axis	2.5 kg·m ² 25.5 kgf·cm·s ²
Drive method		Electric servo drive by AC servo motor
Positioning accuracy		± 0.15 mm
Mass (Note 3)		540 kg
Installation environment		Ambient temperature : 0~45°C Ambient humidity : Normally 75%RH or less (No dew nor frost allowed) Short term 95%RH or less (within one month) Vibration acceleration : 4.9m/s ² (0.5G) or less

Note 1) During short distance motions, the axis speed may not reach the maximum value stated.

Note 2) Max. load capacity at J3 casing is limited by payload at wrist.

Note 3) Without controller.

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